Stabilizers for Nondegenerate Matrices of Boundary Format and Steiner Bundles

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ABSTRACT

In this paper nondegenerate multidimensional matrices of boundary format in $V_0 \otimes \cdots \otimes V_p$ are investigated by their link with Steiner vector bundles on product of projective spaces. For any nondegenerate matrix A the stabilizer for the $\mathrm{SL}(V_0) \times \cdots \times \mathrm{SL}(V_p)$-action, $\mathrm{Stab}(A)$, is completely described. In particular we prove that there exists an explicit action of $\mathrm{SL}(2)$ on $V_0 \otimes \cdots \otimes V_p$ such that $\mathrm{Stab}(A)^0 \subseteq \mathrm{SL}(2)$ and the equality holds if and only if A belongs to a unique $\mathrm{SL}(V_0) \times \cdots \times \mathrm{SL}(V_p)$-orbit containing the identity matrices, according to [1].

Key words: Vector bundles, multidimensional matrices, theory of invariants

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1. Introduction

Let V_j be a complex vector space of dimension $k_j + 1$ for $j = 0, \ldots, p$ with $k_0 = \max_i\{k_i\}$. Gelfand, Kapranov and Zelevinsky in [5] proved that the dual variety of the Segre product $\mathbb{P}(V_0) \times \cdots \times \mathbb{P}(V_p)$ is a hypersurface in $\left(\mathbb{P}^{(k_0+1)\cdots(k_p+1)-1}\right)^{\vee}$ if and only if $k_0 \leq \sum_{i=1}^{p} k_i$. The defining equation of this hypersurface is called the *hyperdeterminant* of format $(k_0+1) \times \cdots \times (k_p+1)$ and is denoted by Det. Moreover the hyperdeterminant is a homogeneous polynomial function on $V_0^{\vee} \otimes \cdots \otimes V_p^{\vee}$ so that the condition Det $A \neq 0$ is meaningful for a $(p+1)$-dimensional matrix $A \in \mathbb{P}(V_0 \otimes \cdots \otimes V_p)$ of format $(k_0+1) \times \cdots \times (k_p+1)$. The hyperdeterminant is an invariant for the natural action of $\mathrm{SL}(V_0) \times \cdots \times \mathrm{SL}(V_p)$ on $\mathbb{P}(V_0 \otimes \cdots \otimes V_p)$, and, in particular, if Det $A \neq 0$ then A is semistable for this action.

We denote by $\mathrm{Stab}(A) \subset \mathrm{SL}(V_0) \times \cdots \times \mathrm{SL}(V_p)$ the stabilizer subgroup of A and by $\mathrm{Stab}(A)^0$ its connected component containing the identity. The stabilizer are well known for $p \leq 1$ (in this case there is always a dense orbit and the orbits are determined by the rank), so that in this paper we assume $p \geq 2$.

It easy to check (see [12], [3]) that the degenerate matrices fill an irreducible variety of codimension $k_0 - \sum_{i=1}^{p} k_i + 1$ and if $k_0 < \sum_{i=1}^{p} k_i$ then all matrices are degenerate. We will assume from now on that A is of *boundary format* i.e., that $k_0 = \sum_{i=1}^{p} k_i$. (A self-contained approach to hyperdeterminant of boundary format matrices can be found in [3].)

For multidimensional boundary format matrices the classical definitions of triangulable, diagonalizable and identity matrices can be easily reformulate in the natural way as follows

Definition 1.1. A $(p+1)$-dimensional matrix of boundary format $A \in V_0 \otimes \cdots \otimes V_p$ is called

  (i) *triangulable* if $\forall j$ there exists a basis $e_0^{(j)}, \ldots, e_{k_j}^{(j)}$ of V_j such that

$$A = \sum a_{i_0,\ldots,i_p} e_{i_0}^{(0)} \otimes \cdots \otimes e_{i_p}^{(p)} \qquad \text{where } a_{i_o,\ldots,i_p} = 0 \text{ for } i_0 > \sum_{t=1}^{p} i_t;$$

  (ii) *diagonalizable* if there exists a basis $e_0^{(j)}, \ldots, e_{k_j}^{(j)}$ of V_j such that

$$A = \sum a_{i_0,\ldots,i_p} e_{i_0}^{(0)} \otimes \cdots \otimes e_{i_p}^{(p)} \qquad \text{where } a_{i_o,\ldots,i_p} = 0 \text{ for } i_0 \neq \sum_{t=1}^{p} i_t;$$

  (iii) an *identity* if there exists a basis $e_0^{(j)}, \ldots, e_{k_j}^{(j)}$ of V_j such that

$$A = \sum a_{i_0,\ldots,i_p} e_{i_0}^{(0)} \otimes \cdots \otimes e_{i_p}^{(p)}$$

  where

$$a_{i_o,\ldots,i_p} = \begin{cases} 0 & \text{for} \quad i_0 \neq \sum_{t=1}^{p} i_t, \\ 1 & \text{for} \quad i_0 = \sum_{t=1}^{p} i_t. \end{cases}$$

Ancona and Ottaviani in [1], considering the natural action of $\mathrm{SL}(V_0) \times \cdots \times \mathrm{SL}(V_p)$ on $\mathbb{P}(V_0 \otimes \cdots \otimes V_p)$, analyze these properties from the point of view of Mumford's Geometric Invariant Theory.

In the same aim, the main result of this paper is the following:

Theorem 1.2. *Let $A \in \mathbb{P}(V_0 \otimes \cdots \otimes V_p)$ be a boundary format matrix with $\mathrm{Det}\, A \neq 0$. Then there exists a 2-dimensional vector space U such that $\mathrm{SL}(U)$ acts over $V_i \simeq$*

$S^{k_i}U$ and according to this action on $V_0 \otimes \cdots \otimes V_p$ we have $\mathrm{Stab}(A)^0 \subseteq \mathrm{SL}(U)$. Moreover the following cases are possible

$$
Stab(A)^0 \simeq
\begin{cases}
0 \\
\mathbb{C} \\
\mathbb{C}^* \\
\mathrm{SL}(2) & \text{(this case occurs if and only if A is an identity)}
\end{cases}
$$

Remark 1.3. We emphasize that $\mathrm{SL}(V_0) \times \cdots \times \mathrm{SL}(V_p)$ is a "big" group, so it is quite surprising that the stabilizer found lies always in the 3-dimensional group $\mathrm{SL}(U)$ without any dependence on p and on $\dim V_i$.

The maximal stabilizer is obtained by the "most symmetric" class of matrices corresponding to the identity matrices. Under the identifications $V_i = S^{k_i}U$ the identity is given by the natural map

$$
S^{k_1}U \otimes \cdots \otimes S^{k_p}U \to S^{k_0}U
$$

which is defined under the assumption $k_0 = \sum k_i$. This explains again why the condition of boundary format is so important.

Ancona and Ottaviani in [1] prove Theorem 1.2 for $p = 2$. We generalize their proof by using the correspondence between nondegenerate boundary format matrices and vector bundles on a product of projective spaces.

Indeed, for any fixed $j \neq 0$, a $(p + 1)$-dimensional matrix $A \in V_0 \otimes \cdots \otimes V_p$ of format $(k_0 + 1) \times \cdots \times (k_p + 1)$ defines a sheaf morphism $f_A{}^{(j)}$ on the product $X = \mathbb{P}^{k_1} \times \cdots \times \widehat{\mathbb{P}^{k_j}} \times \cdots \times \mathbb{P}^{k_p}$

$$
\mathcal{O}_X \otimes V_0^\vee \xrightarrow{f_A{}^{(j)}} \mathcal{O}_X(1, \ldots, 1) \otimes V_j; \tag{1}
$$

and it is easy to prove the following

Proposition 1.4 ([1], [2]). *If a matrix A is of boundary format, then $\mathrm{Det}\,A \neq 0$ if and only if for all $j \neq 0$ the morphism $f_A{}^{(j)}$ is surjective (so $S_A^{\vee\,(j)} = \mathrm{Ker}\,f_A{}^{(j)}$ is a vector bundle of rank $k_0 - k_j$).*

In the particular case $p = 2$ the (dual) vector bundle $S_A{}^{(1)}$ (or $S_A{}^{(2)}$) lives on the projective space $\mathbb{P}^n$, $n = k_2$ (or $n = k_1$) and it is a Steiner bundle as defined in [4] (this case has been investigate in [1]). We shall refer to $S_A^{(j)}$ with the name Steiner also for $p \geq 3$.

The main new technique introduced in this paper is the use of jumping hyperplanes for bundles on the product of $(p - 1)$ projective spaces. For $p \geq 2$ there are two natural ways to introduce them; by the above correspondence, they translate into two different conditions on the associated matrix and that we call weak and strong (see definition 2.1 and 2.6). They coincide when $p = 2$.

Moreover, the loci of weak and strong jumping hyperplanes are invariant for the action of $\mathrm{SL}(V_0) \times \cdots \times \mathrm{SL}(V_p)$ on matrices. By investigating these invariants we derive the proof of Theorem 1.2 and also we obtain a characterization of a particular class of bundles called Schwarzenberger bundles (see [10] for the original definition in the case $p = 2$). Schwarzenberger bundles correspond exactly to such matrices A which verify the equality $\mathrm{Stab}(A)^0 = \mathrm{SL}(2)$ in Theorem 1.2, called identity matrices.

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2. Jumping hyperplanes and stabilizers

Let $p = 2$ and $S := S^1$ be the Steiner bundle on $\mathbb{P}(V_2)$ defined by a matrix $A \in V_0 \otimes V_1 \otimes V_2$ of boundary format, an hyperplane $h \in \mathbb{P}(V_2^\vee)$ is an unstable hyperplane of S if $h^0(S_{|h}^\vee) \neq 0$ (see [1]). By abuse of notations we identify an hyperplane $h \in \mathbb{P}(V_2^\vee)$ with any vector $h' \in V_2$ such that $\langle h' \rangle = h$.

In particular, $\mathcal{H}^0(S^\vee(t))$ identifies to the space of $(k_0 + 1) \times 1$-column vectors v with entries in $S^t V_2$ such that $Av = 0$, and a hyperplane h is unstable for S if and only if there are nonzero vectors v_0 of size $(k_0 + 1) \times 1$ and v_1 of size $(k_1 + 1) \times 1$ both with constant coefficients such that

$$Av_0 = v_1 h; \tag{2}$$

the tensor $\mathcal{H} = v_0 \otimes v_1$ is called an unstable (or jumping) hyperplane for the matrix A.

For $p \geq 3$ there are at least two ways to define a jumping hyperplane. We will call them weak and strong jumping hyperplanes.

Definition 2.1. $\mathcal{H} = v_0 \otimes v_j \otimes h \in V_0 \otimes V_j \otimes \widehat{V}^j$ (where $\widehat{V}^j = V_1 \otimes \cdots \otimes \widehat{V_j} \otimes \cdots \otimes V_p$) is a (j)-*weak jumping hyperplane* for A if $\exists\, v_0, w_1, \ldots, w_{k_0}$ basis of V_0 such that

$$A = v_0 \otimes v_j \otimes h + \sum_{i=1}^{k_0} w_i \otimes \cdots \tag{3}$$

where $h \in \widehat{V}^j$ generate an hyperplane for $\mathbb{P}^{k_1} \times \cdots \times \widehat{\mathbb{P}^{k_j}} \times \cdots \times \mathbb{P}^{k_p} \subset \mathbb{P}(V_1 \otimes \cdots \otimes \widehat{V_j} \otimes \cdots \otimes V_p)$ (that, by abuse of notations, we call also h).

Remark 2.2. The expression (3) means, as in the case $p = 2$, that $H^0(\mathrm{Ker}\, f_{A|h}^{(j)}) \neq 0$ (i.e., by definition, h is a jumping hyperplane for the bundle $S_A{}^{(j)}$).

If $\mathcal{H} = v_0 \otimes v_j$ is a (j)-weak jumping hyperplane for A then the map:

$$V_0 \otimes \cdots \otimes V_p \to (V_0/_{\langle v_0 \rangle}) \otimes \cdots \otimes (V_j/_{\langle v_j \rangle}) \otimes \cdots \otimes V_p$$
$$A \mapsto A'_j$$

gives an elementary transformation [8].

Remark 2.3. A'_j is again of boundary format. In particular, after a basis has been chosen, A'_j is obtained by deleting two directions in A.

Proposition 2.4. *If A'_j is defined as above*

$$\operatorname{Det} A \neq 0 \Rightarrow \operatorname{Det} A'_j \neq 0$$

Proof. If $X := \mathbb{P}^{k_1} \times \cdots \times \widehat{\mathbb{P}^{k_j}} \times \cdots \times \mathbb{P}^{k_p}$ and h is the hyperplane defined in 2.1 associated to $\mathcal{H}$, the map $S_A{}^{(j)} \to \mathcal{O}_h$ induced by a non zero section of $S_A{}^{(j)}$ is surjective (the same proof of [14, prop. 2.1] works).

Since codim $h = 1$, then its kernel $S'^{(j)}$ is locally free sheaf [11] of rank $k_0 - k_j - 1$ on X and it is the Steiner bundle associated to the matrix $A^{(j)}$ as the snake-lemma applied to the following exact diagram shows

$$
\begin{array}{ccccccccc}
& & & & & & 0 & & \\
& & & & & & \downarrow & & \\
& & & & & & S'^{(j)} & & \\
& & & & & & \downarrow & & \\
0 & \longrightarrow & \mathcal{O}_X(-1,\ldots,-1) \otimes V_j^{\vee} & \xrightarrow{f_A{}^{(j)}} & \mathcal{O}_X \otimes V_0^{\vee} & \longrightarrow & S_A{}^{(j)} & \longrightarrow & 0 \\
& & \downarrow & & \downarrow & & \downarrow & & \\
0 & \longrightarrow & \mathcal{O}_X(-1,\ldots,-1) & \longrightarrow & \mathcal{O}_X & \longrightarrow & \mathcal{O}_h & \longrightarrow & 0 \\
& & \downarrow & & \downarrow & & \downarrow & & \\
& & 0 & & 0 & & 0 & &
\end{array}
$$

i.e., $S'^{(j)} = S_{A'_j}{}^{(j)}$ and by Proposition 1.4 the result follows. $\qquad\square$

Remark 2.5. If $W(S_A^{(j)})$ is the set of jumping hyperplanes of the bundle $S_A^{(j)}$, then the exact sequence (dual to the last column of the above diagram)

$$0 \to S_A^{(j)\vee} \to S_{A'_j}^{(j)\vee} \to \mathcal{O}_X(1,\ldots,1) \to 0$$

shows that $W(S_A^{(j)}) \subset W(S_{A'_j}^{(j)}) \cup \{h\}$

Definition 2.6. $\mathcal{H} = v_0 \otimes v_1 \otimes \cdots \otimes v_p$ is a *strong jumping hyperplane* for A if $\exists\, v_0, w_1, \ldots, w_{k_0}$ basis of V_0 such that

$$A = v_0 \otimes v_1 \otimes \cdots \otimes v_p + \sum_{i=1}^{k_0} w_i \otimes \cdots$$

Remark 2.7. If $\mathcal{H}$ is a strong jumping hyperplane then $\mathcal{H}$ defines a (j)-weak jumping hyperplane for all $j = 1, \ldots, p$; in particular for a strong jumping hyperplane there are many elementary transformations.

Remark 2.8. For $p = 2$ the notations of strong jumping hyperplane and of weak jumping hyperplane coincide with each other (see [1]).

Example 2.9 *(the identity).* Fixed a basis $e_0^{(j)}, \ldots, e_{k_j}^{(j)}$ in V_j for all j, the identity matrix is represented by

$$ I := \sum_{\substack{i_0 = i_1 + \cdots + i_p \\ 0 \leq i_j \leq k_j}} e_{i_0}^{(0)} \otimes \cdots \otimes e_{i_p}^{(p)}. $$

Let $t_0, \ldots, t_{k_0}$ be any distinct complex numbers. Let w be the $(k_0 + 1) \times (k_0 + 1)$ Vandermonde matrix whose (i, j) entry is $t_j^{(i-1)}$, so acting with w over V_0, we have:

$$ e_j^{(0)} = \sum_{s=0}^{k_0} \bar{e}_s^{(0)} t_s^j $$

Then substituting

$$ I = \sum_{\substack{i_0 = i_1 + \cdots + i_p \\ s = 0, \ldots k_0}} \bar{e}_{i_0}^{(0)} t_s^{i_0} \otimes e_{i_1}^{(1)} \otimes \cdots \otimes e_{i_p}^{(p)} $$

$$ = \sum_{s=0}^{k_0} \bar{e}_s^0 \otimes \left(\sum_{i_1=0}^{k_1} e_{i_1}^{(1)} t_s^{i_1} \right) \otimes \cdots \otimes \left(\sum_{i_p=0}^{k_p} e_{i_p}^{(p)} t_s^{i_p} \right) $$

Thus, since t_i have no restrictions, I has infinitely many strong jumping hyperplane.

We call *Schwarzenberger bundle* the vector bundle associated to I (in fact in the case $p = 2$ it is exactly the same introduced by Schwarzenberger in [10], see also [1]).

Proposition 2.10. *Let A be a boundary format matrix with $\operatorname{Det} A \neq 0$. If A has $N \geq k_0 + 3$ strong jumping hyperplanes then it is an identity.*

Proof. In the case $p = 2$ the statement is proved in [1, Theorem 5.13] or in [14, Theorem 3.1]. Chosen V_0 and other two vector spaces among $V_1, \ldots, V_p$ (say V_1 and V_2), one may perform several elementary transformations with V_0 and all the others so that we get $A' \in V'_0 \otimes V_1 \otimes V_2$ boundary format matrix with $\operatorname{Det} A' \neq 0$ and $N' \geq k'_0 + 3$ strong jumping hyperplanes, then A' is an identity.

As in the above example, one can change the hyperplane giving the elementary transformation, so that for all N strong jumping hyperplanes we get $t_1, \ldots, t_N$ distinct complex numbers and corresponding suitable basis of V_1 and V_2:

$$ \bar{e}_0^{(1)}, \ldots, \bar{e}_{k_1}^{(1)} $$
$$ \bar{e}_0^{(2)}, \ldots, \bar{e}_{k_2}^{(2)} $$

such that the hyperplanes are given by

$$\sum_{i=0}^{k_1} \bar{e}_i^{(1)} t_j^i \quad \text{and} \quad \sum_{i=0}^{k_2} \bar{e}_i^{(2)} t_j^i \quad \text{for} j = 1, \ldots N$$

Now, changing V_1 and V_2 with the pairs V_1, V_j $(j = 1, \ldots p)$ we get

$$A := \sum_{s=0}^{k_0} \bar{e}_s^0 \otimes \Big(\sum_{i_1=0}^{k_1} e_{i_1}^{(1)} t_s^{i_1} \Big) \otimes \cdots \otimes \Big(\sum_{i_p=0}^{k_p} e_{i_p}^{(p)} t_s^{i_p} \Big)$$

showing that A is an identity. $\hfill \square$

Proposition 2.11. *Two nondegenerate boundary format matrices having in common $k_0 + 2$ distinct strong jumping hyperplanes determine isomorphic Steiner bundles for every j.*

Proof. In the case $p = 2$ the statement is proved in [1, Theorem 5.3]. Chosen V_0 and other two vector spaces among $V_1, \ldots, V_p$ (say V_1 and V_2), one may perform several elementary transformations with V_0 and all the others so that we get $A' \in V'_0 \otimes V_1 \otimes V_2$ boundary format matrix with $\mathrm{Det}\, A' \neq 0$ and $N' = k'_0 + 2$ strong jumping hyperplanes, then $S_{A'}^{(j)}$ is uniquely determined for every j. Now, changing V_1 and V_2 with the pairs V_1 and V_j $(j = 2, \ldots, p)$ we detect all the 3-dimensional submatrices of A which give bundles uniquely determined, so also $S_A^{(j)}$ is uniquely determined for every j. $\hfill \square$

Remark 2.12. In the case $p = 2$ we know that $k_0 + 2$ jumping hyperplanes give an existence condition for the bundles $S_A^{(j)}$ (they are logarithmic bundles, see [1]) but in the case $p \geq 3$ there is not an analog existence result.(The previous proposition gives only the uniqueness.)

The following is a classical result (see for instance [7, prop. 9.4, page 102], or [4, Theorem 6.8]).

Proposition 2.13. *All nondegenerate matrices of type $2 \times k \times (k + 1)$ are $\mathrm{GL}(2) \times \mathrm{GL}(k) \times \mathrm{GL}(k + 1)$ equivalent, or equivalently every surjective morphism of vector bundles on $\mathbb{P}^1$*

$$\mathcal{O}_{\mathbb{P}^1}^{k+1} \to \mathcal{O}_{\mathbb{P}^1}(1)^k$$

is represented by an identity matrix.

We recall now the following

Proposition 2.14 ([1]). *Let $A \in V_0 \otimes \cdots \otimes V_p$ A be a $(p + 1)$-dimensional matrix of boundary format the following conditions are equivalent:*

  (i) *A is an identity;*

(ii) *there exist a vector space U of dimension 2 and isomorphisms $V_j \simeq S^{k_j}U$ such that A belongs to the unique one dimensional $\mathrm{SL}(U)$-invariant subspace of $S^{k_0}U \otimes \cdots \otimes S^{k_p}U$.*

The equivalence between (i) and (ii) follows easily from the following remark: the matrix A satisfies the condition (ii) if and only if it corresponds to the natural multiplication map $S^{k_1}U \otimes \cdots \otimes S^{k_p}U \to S^{k_0}U$ (after a suitable isomorphism $U \simeq U^\vee$ has been fixed). We notice that by the Clebsch-Gordan decomposition of the tensor product there is a unique $\mathrm{SL}(U)$-invariant map as above.

Remark 2.15. If A is not an identity, an element $g \in \mathrm{Stab}(A)$ preserves a (j)-weak jumping hyperplane h and it induces $\bar{g} \in \mathrm{SL}(V_0/_{\langle g(v_0) \rangle}) \times \mathrm{SL}(V_1) \times \cdots \times \mathrm{SL}(V_j/_{\langle g(v_j) \rangle}) \times \cdots \times \mathrm{SL}(V_p)$ such that $g \cdot A$ projects to $\bar{g} \cdot A'_j$ and the elementary transformation behaves well with respect to the action of g.

For every integer j, let $D_{j,\mathrm{strong}}(A)$ be the *locus of (j)-strong directions of A* defined as

$$\{\, \langle v_j \rangle \in \mathbb{P}(V_j^\vee) \mid \forall i \neq j \; \exists \; v_i \in V_i \text{ such that}$$
$$v_0 \otimes \cdots \otimes v_p \text{ is a strong jumping hyperplane for } A \,\}.$$

We recall that (see for details [1]) for boundary format matrices the following conditions are equivalent

(i) $A \in V_0 \otimes \cdots \otimes V_p$ is diagonal,

(ii) $\mathbb{C}^* \subset \mathrm{Stab}(A)$,

(iii) there exist a vector space U of dimension 2, a subgroup $\mathbb{C}^* \subset \mathrm{SL}(U)$ and isomorphisms $V_j \simeq S^{k_j}U$ such that A is a fixed point of the induced action of $\mathbb{C}^*$.

Then, the same proofs of Corollaries 6.9–6.10 and Lemmas 6.12–6.13 of [1] work also in the $(p+1)$-dimensional case, by replacing V by V_j and $W(S)$ by $D_{j,\mathrm{strong}}(A)$. More precisely we have:

Corollary 2.16. *Let A be a boundary format nondegenerate matrix. If $\mathbb{C}^* \subset \mathrm{Stab}(A)$ then for every j the $\mathbb{C}^*$-action on V_j has exactly $k_j + 1$ fixed points whose weights are proportional to $-k_j, -k_j + 2, \ldots, k_j - 2, k_j$.*

Remark 2.17. More in general, the $\mathbb{C}^*$-action on V (where V is a $n + 1$-dimensional vector space) has exactly $n + 1$ fixed points whose weights are proportional to $-n, -n + 2, \ldots, n - 2, n$ if and only if there exist a vector space U of dimension 2 such that $\mathbb{C}^* \subset \mathrm{SL}(U)$ and $V \simeq S^nU$.

Corollary 2.18. *Let A be a boundary format nondegenerate matrix such that $\mathbb{C}^* \subset \mathrm{Stab}(A)$. Then either A is an identity or $D_{j,strong}(A)$ has only two closed points, namely the two fixed points of the dual $\mathbb{C}^*$-action on $\mathbb{P}(V_j^\vee)$ having minimum and maximum weights.*

Lemma 2.19. *Let U be a 2-dimensional vector space, and $\forall j\ C_j \simeq \mathbb{P}(U) \to \mathbb{P}(S^{k_j}U)$ be the $\mathrm{SL}(U)$-equivariant embedding (whose image is a rational normal curve). Let $\mathbb{C}^* \subset \mathrm{SL}(U)$ act on $\mathbb{P}(S^{k_j}U)$. We label the $k_j + 1$ fixed points P_i, $i = -k_j + 2n$, $n = 0, \ldots, k_j$, of the $\mathbb{C}^*$-action with an index proportional to its weight. Then P_{-k_j}, P_{k_j} lie on C_j and $P_{-k_j+2n} = T^n P_{-k_j} \cap T^{k_j - n} P_{k_j}$, where T^n denotes the n-dimensional osculating space to C_j.*

Lemma 2.20. *Let A be a boundary format nondegenerate matrix. If there are two different one-parameter subgroups $\lambda_1, \lambda_2 : \mathbb{C}^* \to Stab(A)$ then A is an identity.*

Proof of Theorem 1.2. We proceed by induction on k_0.

If $k_0 = 2$ the theorem is true by Proposition 2.13.

When $\mathrm{Stab}(A)^0$ contains only the identity the result is trivial hence we may suppose that $\dim \mathrm{Stab}(A)^0 \geq 1$ then, according to [1, Theorem 2.4], the matrix A is triangulable and there exists at least one strong jumping hyperplane $\mathcal{H} = v_0 \otimes \cdots \otimes v_p$.

We may also suppose that the number of strong jumping hyperplanes is finite otherwise A is an identity (Proposition 2.10), hence $\mathcal{H}$ is $\mathrm{Stab}(A)^0$-invariant. Let A_1' be the image of A by the elementary transformation associated to the (1)-weak jumping hyperplane defined by $\mathcal{H}$ (we choose $j = 1$ to have simpler notations). The matrix A_1' belongs to $V_0' \otimes V_1' \otimes V_2 \otimes \cdots \otimes V_p$ where $V_0' = V_0 / \langle v_0 \rangle$ and $V_1' = V_1 / \langle v_1 \rangle$, it is nondegenerate and of boundary format then, by induction, there exists a 2-dimensional vector space U such that

$$V_0' \simeq S^{k_0 - 1}(U), \quad V_1' \simeq S^{k_1 - 1}(U) \quad \text{and} \quad V_i = S^{k_i}(U) \quad \text{for all} \quad i \geq 2$$

and $\mathrm{Stab}(A_1')^0 \subseteq \mathrm{SL}(U)$ (by using essentially the same argument we could work in $\mathrm{GL}(V_0) \times \cdots \times \mathrm{GL}(V_p)$).

Since A_1' is obtained from the matrix A after the choice of two directions, any element which stabilizes A also stabilizes A_1', so $\mathrm{Stab}(A)^0 \subseteq \mathrm{Stab}(A_1')^0$. Hence $\mathrm{Stab}(A)^0 \subseteq \mathrm{SL}(U)$ and $\mathrm{SL}(U)$ acts on V_i according to $V_i \simeq S^{k_i}U$ for $i \geq 2$, by the inductive hypothesis.

Now, we claim that the action of $\mathrm{SL}(U)$ can be lifted to the whole $V_0 \otimes \cdots \otimes V_p$.

Indeed, the above considered elementary transformation gives the decomposition $V_0 = V_0' \oplus \mathbb{C}$ and $V_1 = V_1' \oplus \mathbb{C}$.

If $\phi : \mathbb{C}^* \to \mathrm{GL}(V_i')$ is the natural action of $\mathbb{C}^* \subset \mathrm{SL}(U)$ on $V_i' = S^{k_i - 1}U$ (for $i = 0, 1$) with k_i fixed points having weights $-k_i + 1, -k_i + 3, \ldots, k_i - 1$, we can construct an action $\psi : \mathbb{C}^* \to \mathrm{GL}(V_i' \oplus \mathbb{C})$ on V_i defined by

$$t \mapsto \begin{pmatrix} t^{-1}\phi(t) & 0 \\ 0 & t^{k_i} \end{pmatrix}$$

having $k_i + 1$ fixed points with weights $-k_i, -k_i + 2, \ldots, k_i$. hence, by remark 2.17, the statement follows.

In the case $\mathrm{Stab}(A)^0 = \mathrm{SL}(2)$, the action of $\mathrm{SL}(U)$ satisfies definition 2.14, proving that A is an identity.

Now, as in [1], consider the Levi decomposition $Stab(A)^0 = M \cdot R$ where R is the radical and M is maximal semisimple. If A is not an identity (i.e., $\mathrm{Stab}^0(A) \neq \mathrm{SL}(2)$) then $M = 0$ and $\mathrm{Stab}(A)^0$ is solvable hence by the Lie Theorem it is contained (after a convenient basis has been chosen) in the subgroup of upper triangular matrices

$$T = \left\{ \begin{pmatrix} a & b \\ 0 & \frac{1}{a} \end{pmatrix} \, \middle| \, a \in \mathbb{C}^*, b \in \mathbb{C} \right\}.$$

If there is a subgroup $\mathbb{C}^*$ properly contained in $\mathrm{Stab}(A)^0$ then there is a conjugate of $\mathbb{C}^*$ different from itself and this is a contradiction by the Lemma 2.20. If $\mathrm{Stab}(A)^0$ does not contain proper subgroups $\mathbb{C}^*$ then it is isomorphic to

$$\mathbb{C} \simeq \left\{ \begin{pmatrix} 1 & b \\ 0 & 1 \end{pmatrix} \, \middle| \, b \in \mathbb{C} \right\}. \qquad \Box$$

Remark 2.21. Throughout this paper we work only on nondegenerate matrices. Indeed, in the proofs we apply the induction strategy (hence the results of [1]) and the correspondence between matrices and vector bundles described in Proposition 1.4.

The characterization of the stabilizer of degenerate matrices is still an open problem. Another interesting problem is the study of the stabilizer of general multidimensional matrices (and not necessarily of boundary format).

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